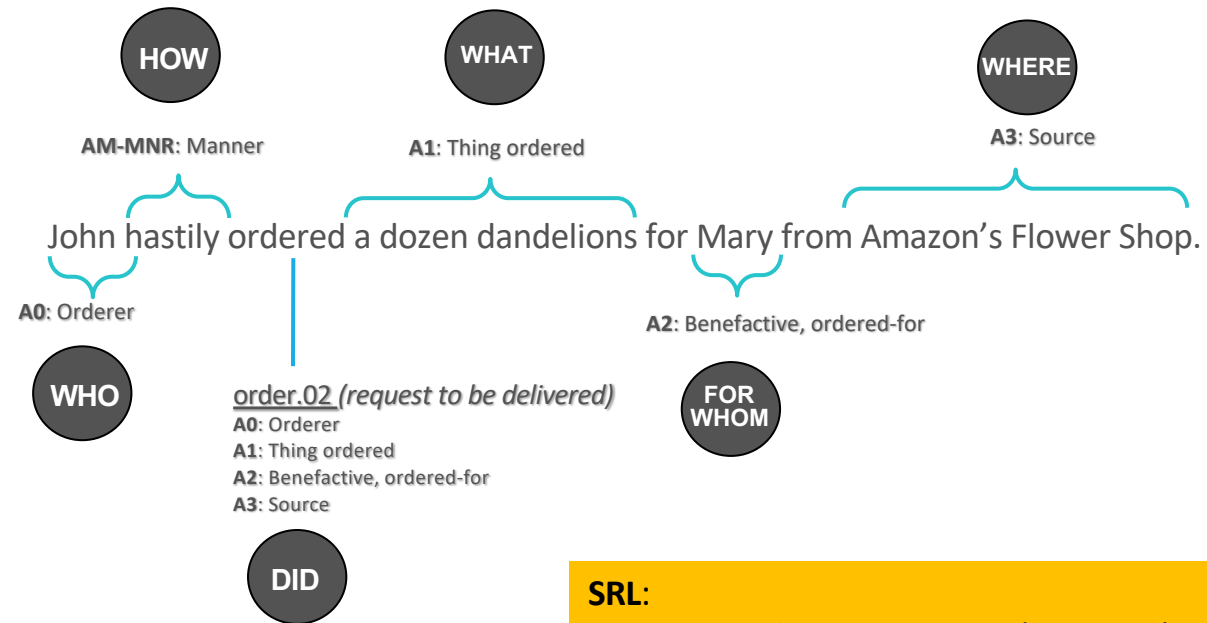


Active Learning for Black-Box Semantic Role Labeling with Neural Factors

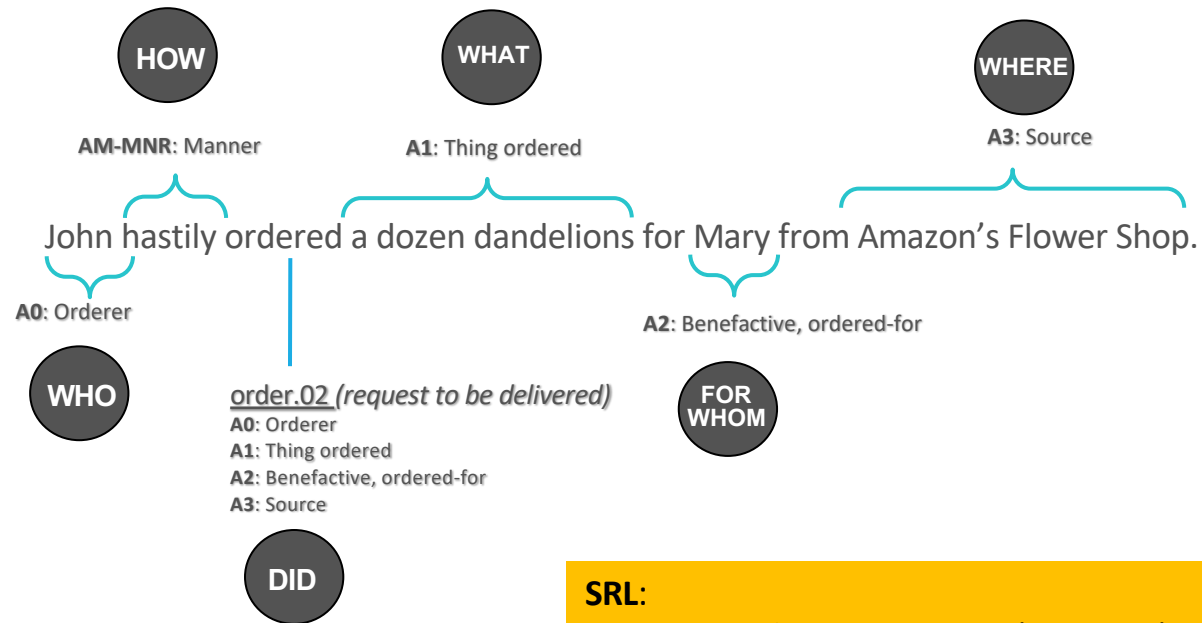
Chenguang Wang, Laura Chiticariu, Yunyao Li
IBM Research – Almaden



SRL:

Recover predicate-argument (semantic) structure from text

Who did what to whom, when, where and how?



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General Applications



Information Extraction



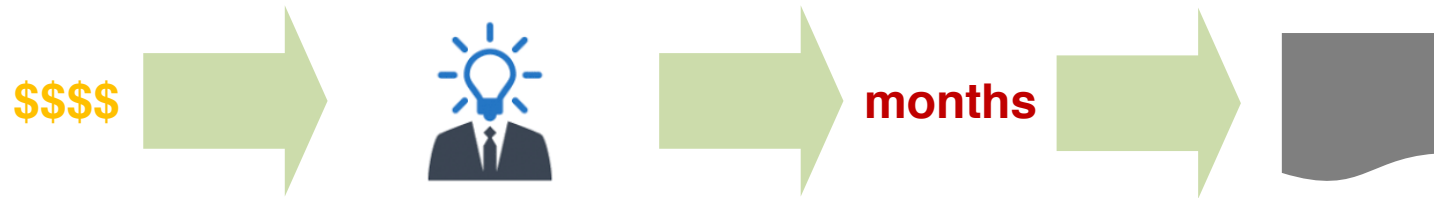
WIKIPEDIA
The Free Encyclopedia
Knowledge Base Construction



Question Answering

- **Key to improving SRL**
 - More SRL Labeled data

- **Key to improving SRL**
 - More SRL Labeled data
- **Way to generate SRL labeled data**

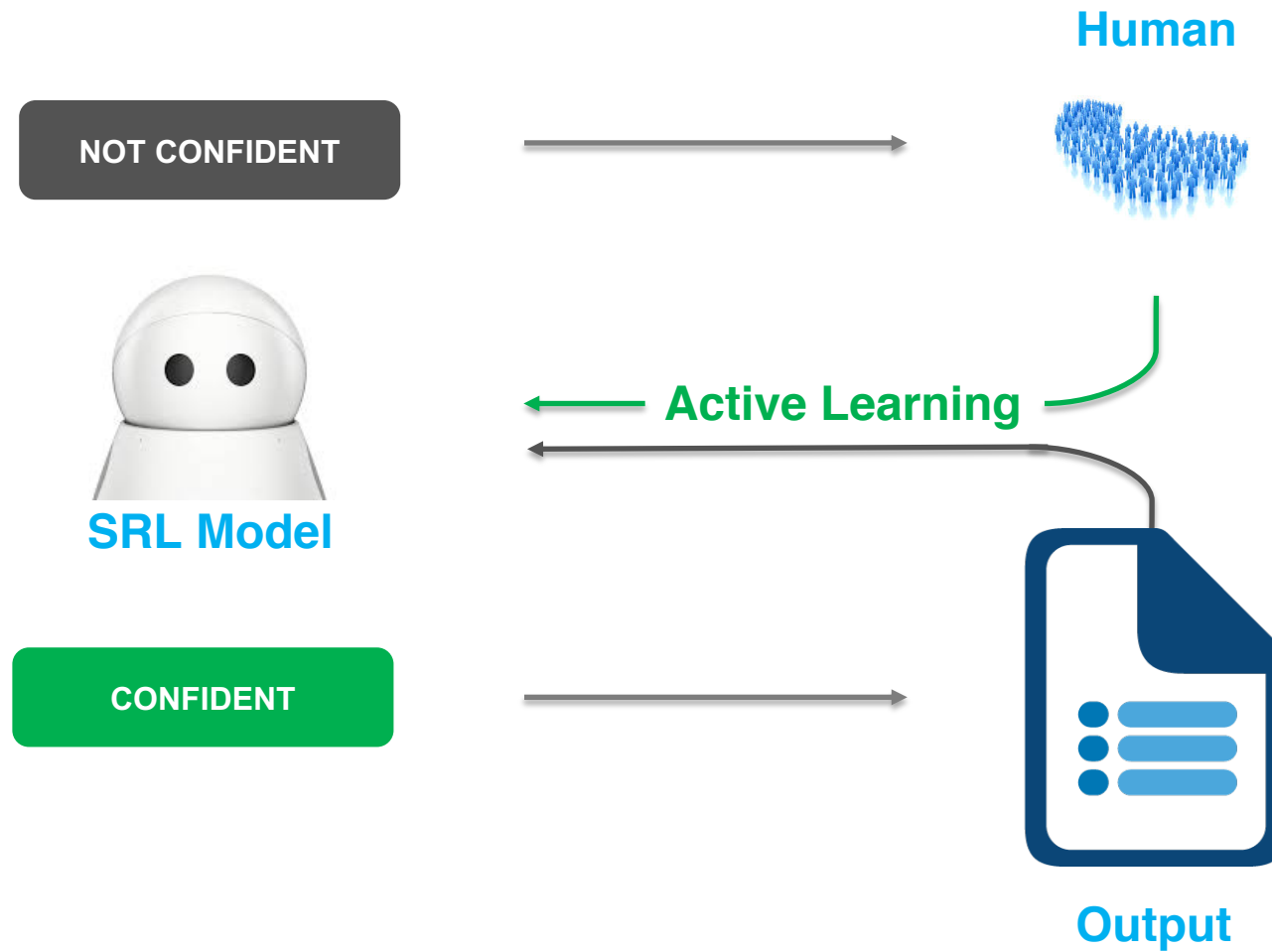


- Label by experts
 - Issue: cost is high
- Examples
 - PropBank, FrameNet

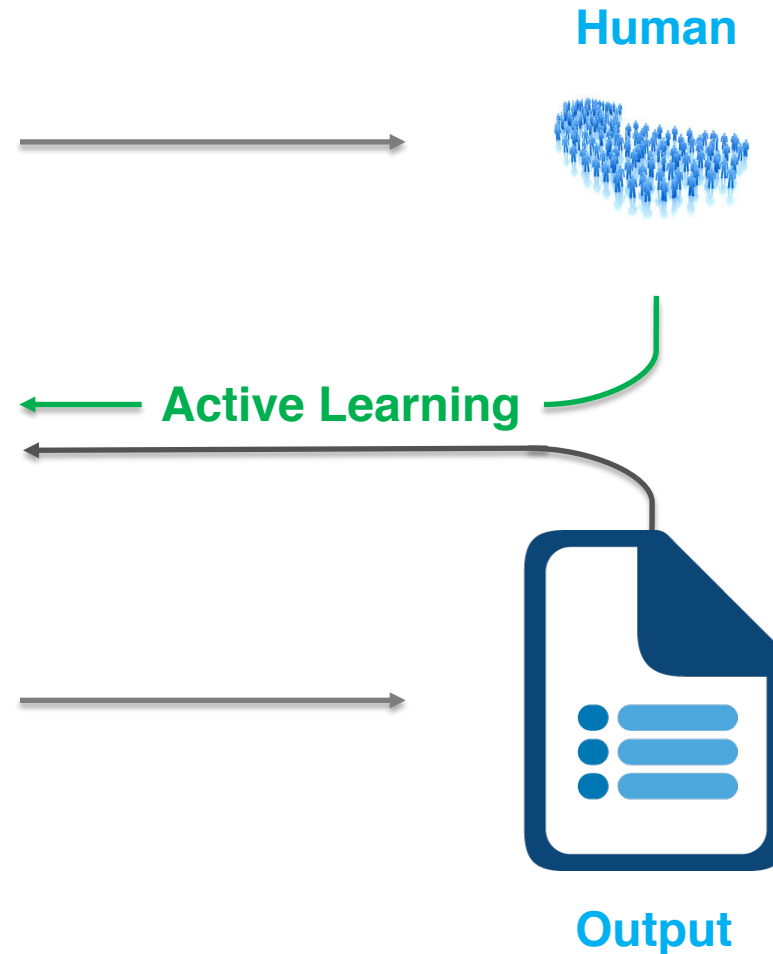
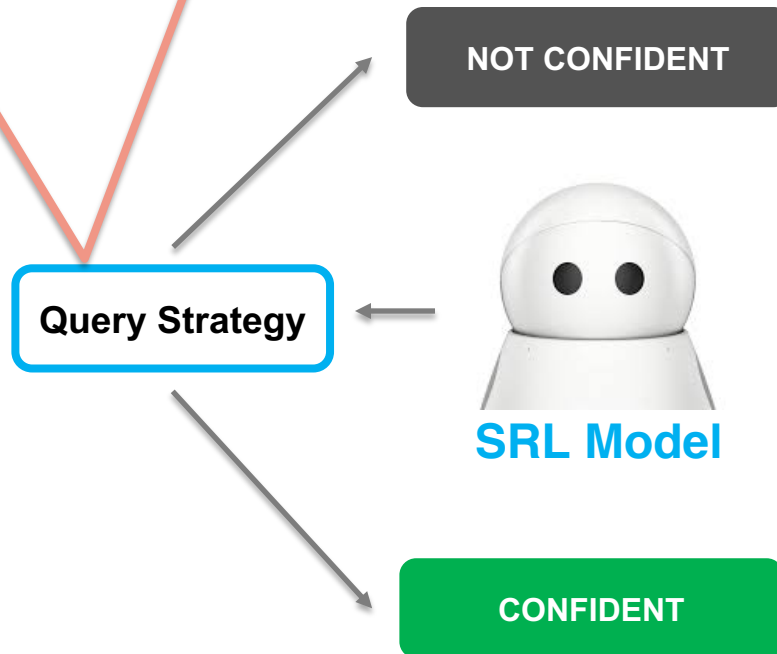
- Goal of Active Learning
 - carefully select the training data based on **query strategy** from which the model is being learnt in order to **achieve good performance with less training data**

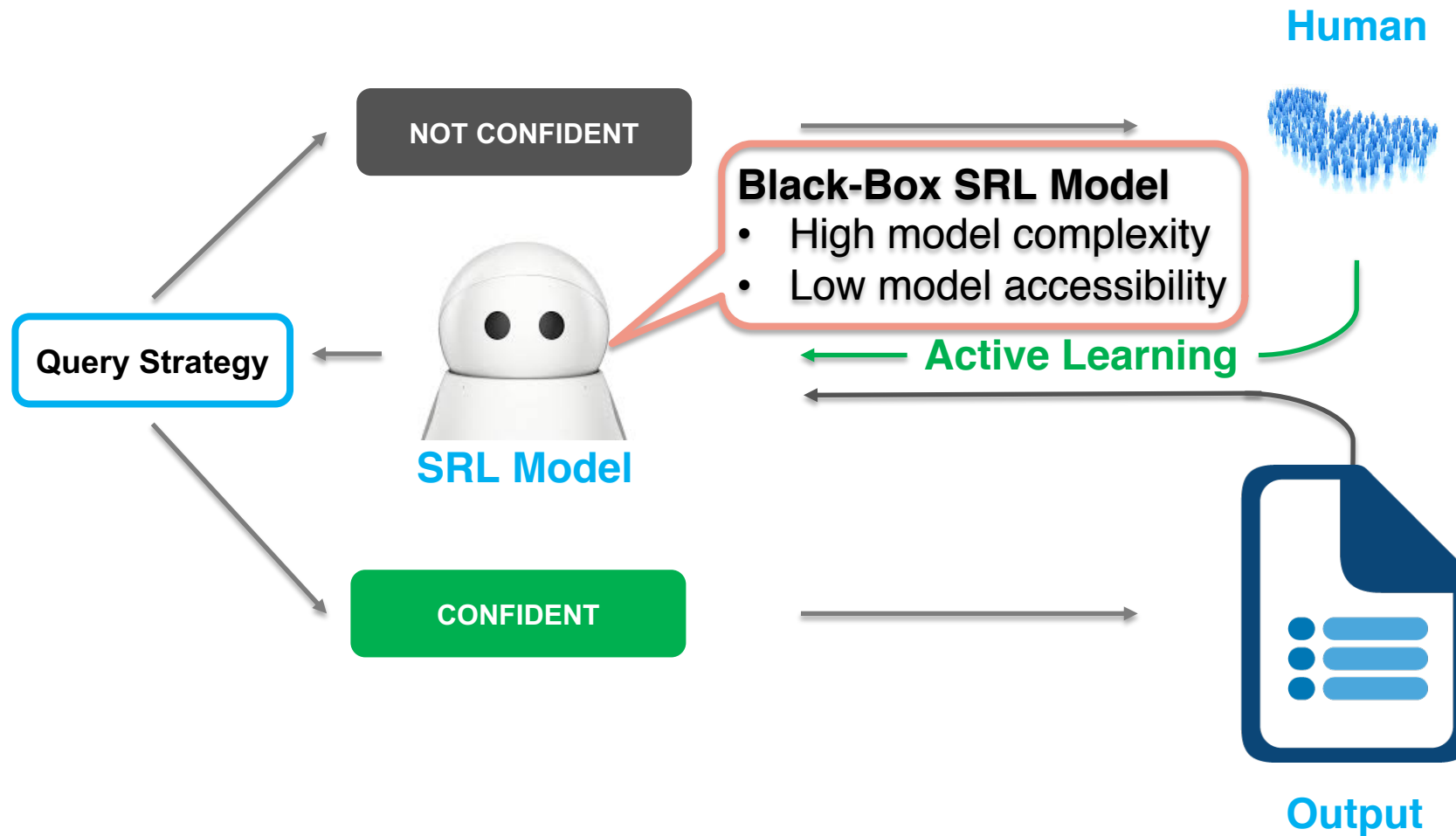
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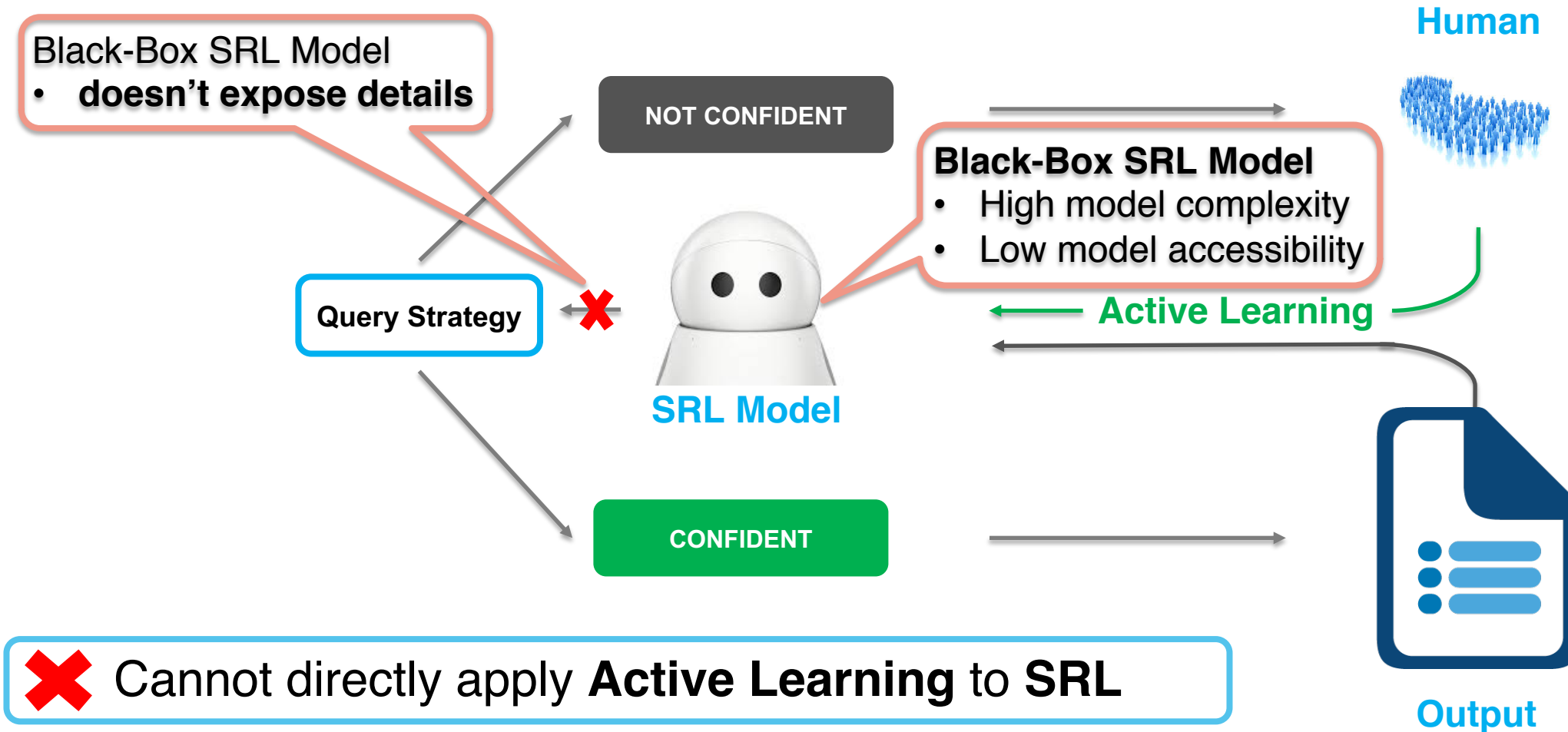
How about directly apply **Active Learning** to **SRL**?

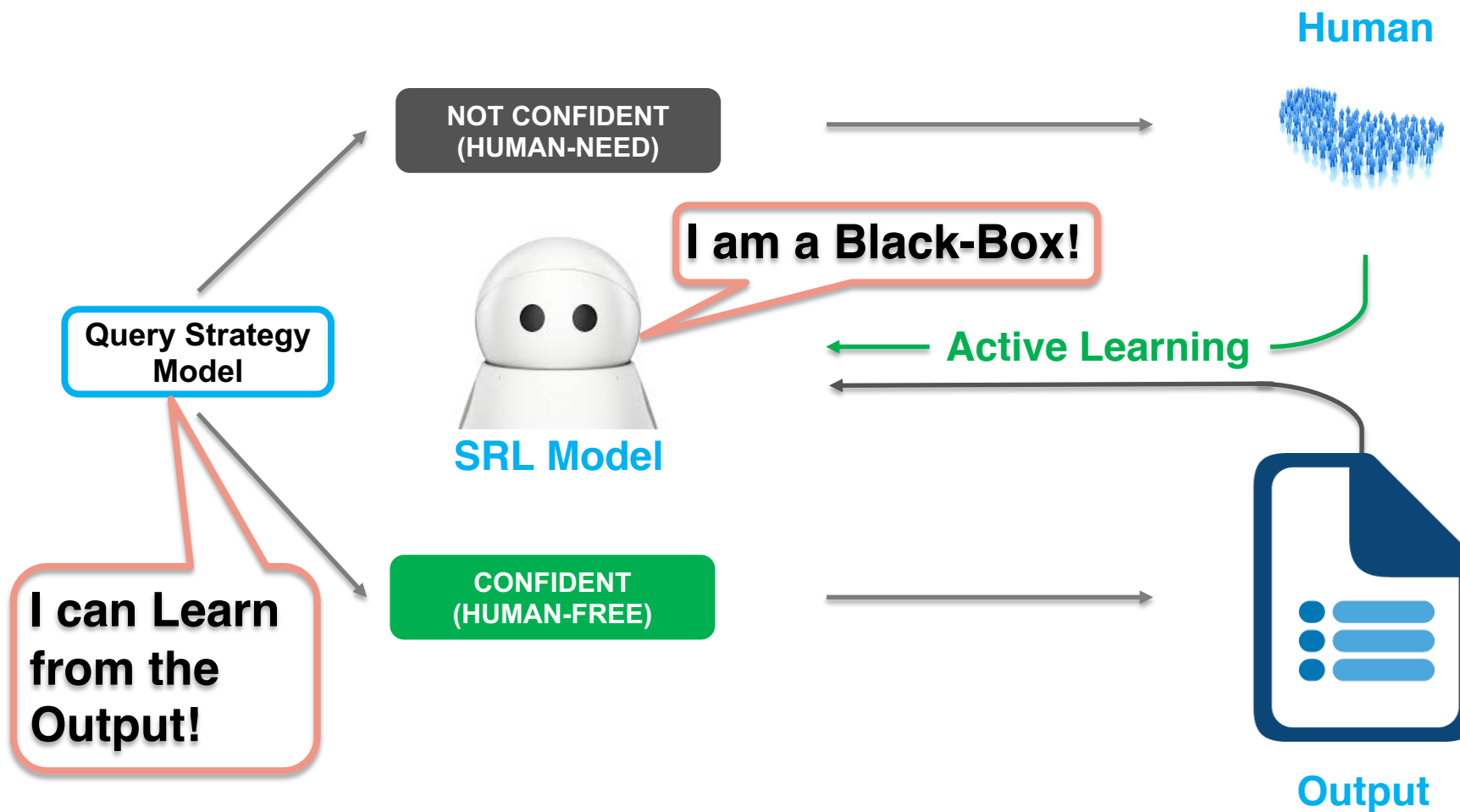


- **Core of active learning** (e.g., uncertainty sampling/query-by-committee).
- **Require model details to compute.**



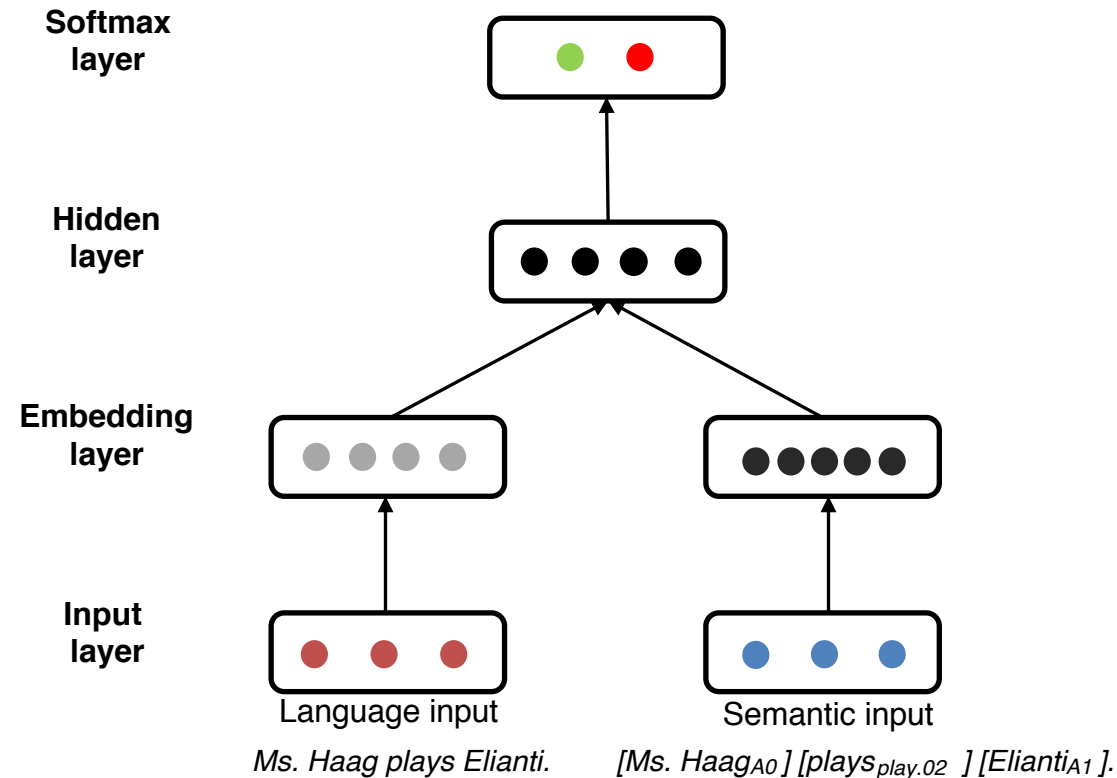






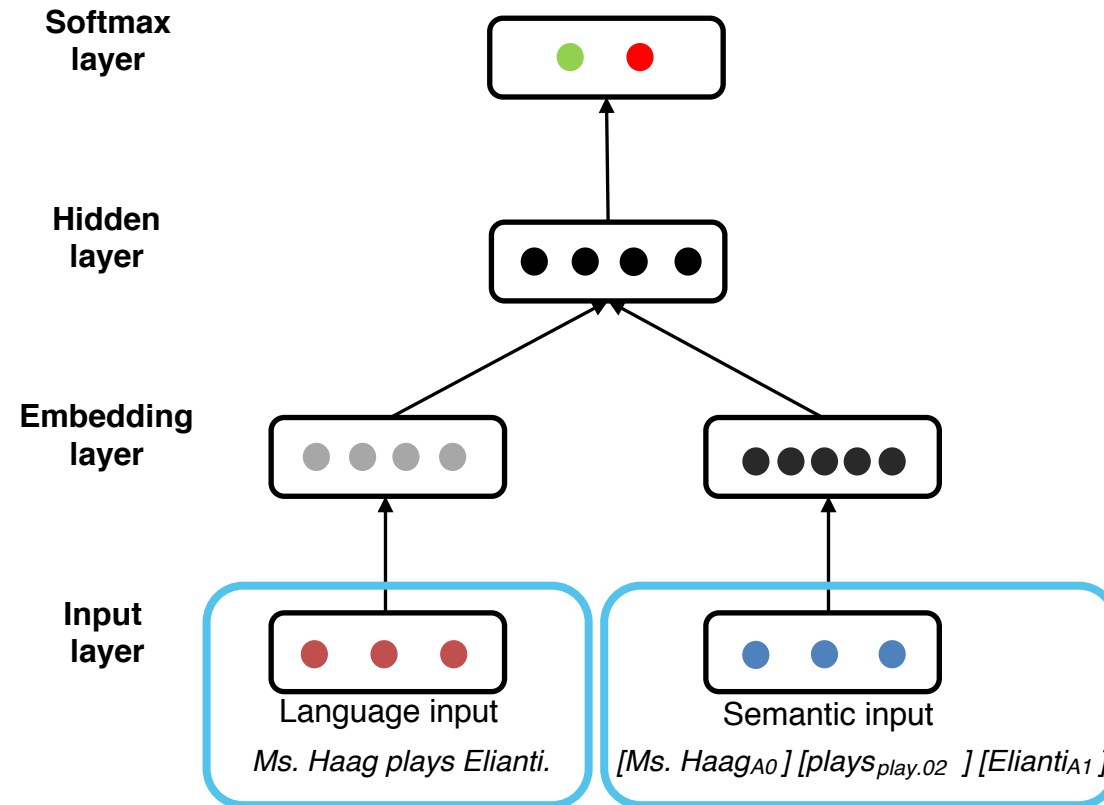
Classification Model: Classify a predicted SRL label based on the model output

- **Human-free SRL** label if the predicted SRL label is likely to be the gold SRL label
- **Human-need SRL** label otherwise



Input Layer

- **Language input:** Text/sentence
- **Semantic input:** Argument/role label, predicate/frame label



Embedding Layer

- Language embedding:

$$\mathcal{L}_{\vec{e}_L} = \sum_{i=1}^T \sum_{-c \leq j-i \leq c, j-i \neq 0} \log q(w_j | w_i)$$

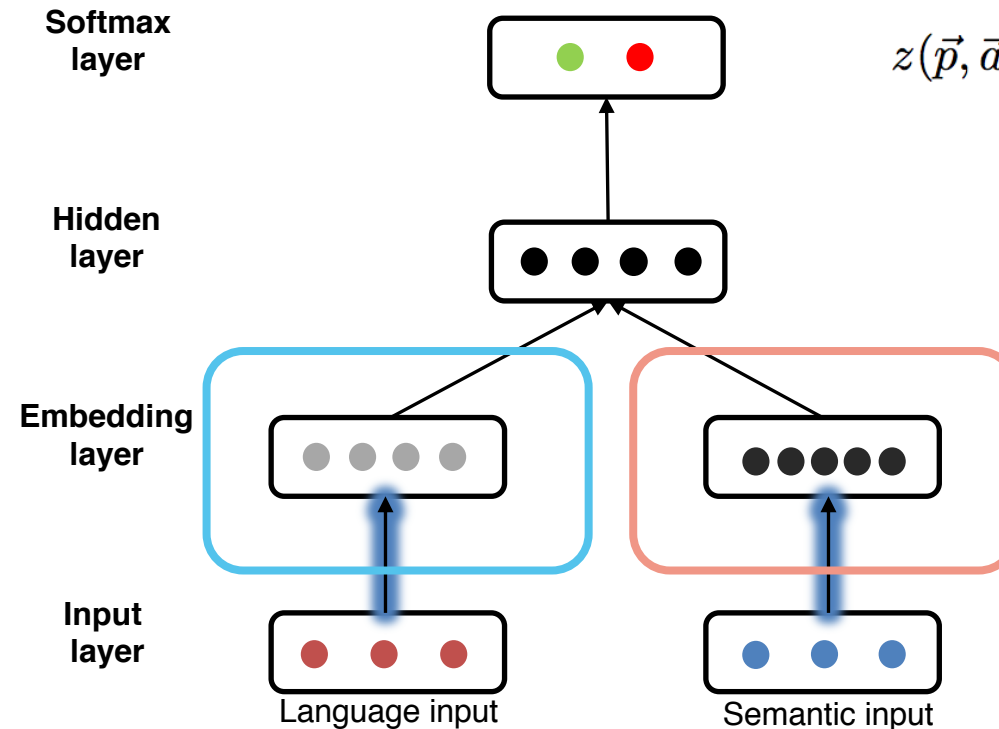
- Semantic embedding:

$$\mathcal{L}_{\vec{e}_S} = \sum_{p \in \mathcal{P}} \sum_{a \in \mathcal{A}} \log(q(a|p) + q(p|a))$$

$$q(w_j | w_i) = \frac{\exp(\vec{v}'_j T \vec{v}_i)}{\sum_{k=1}^{|W|} \exp(\vec{v}'_k T \vec{v}_i)}$$

$$q(a|p) = \frac{\exp\{z(\vec{p}, \vec{a})\}}{\sum_{a' \in \mathcal{A}} \exp\{z(\vec{p}, \vec{a}')\}}$$

$$z(\vec{p}, \vec{a}) = b - \frac{1}{2} \|\vec{p} - \vec{a}\|^2$$

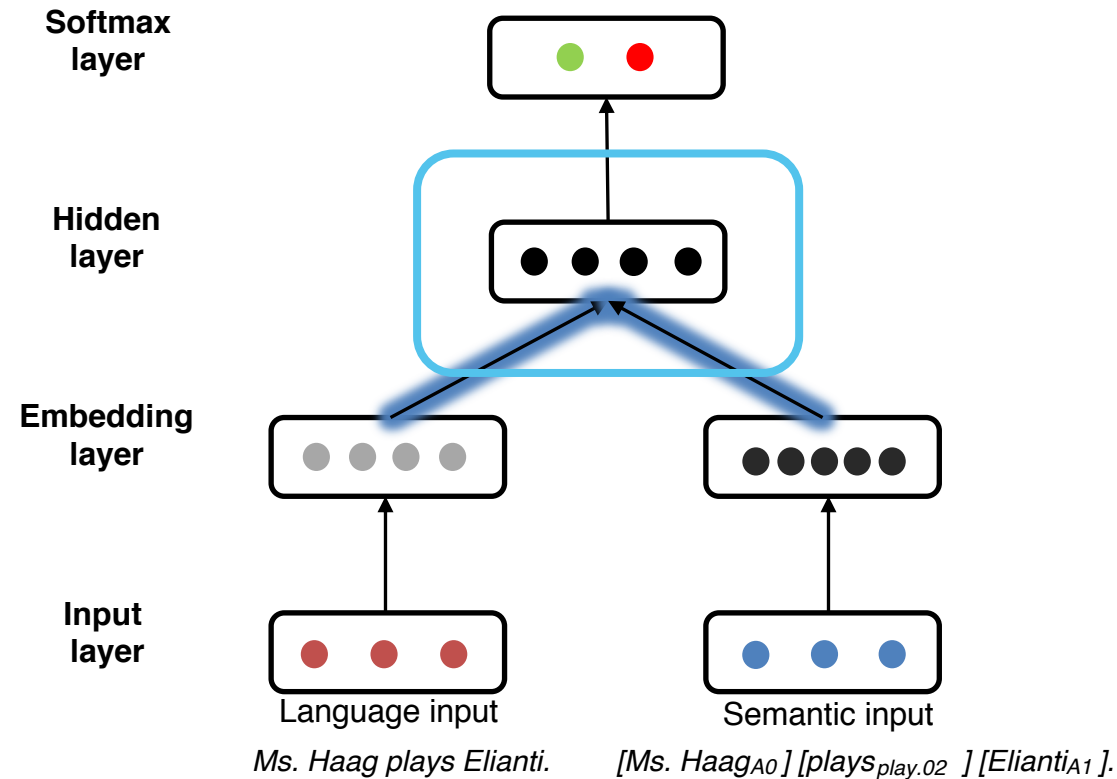


Ms. Haag plays Elianti.

[Ms. Haag_{A0}] [plays_{play.02}] [Elianti_{A1}].

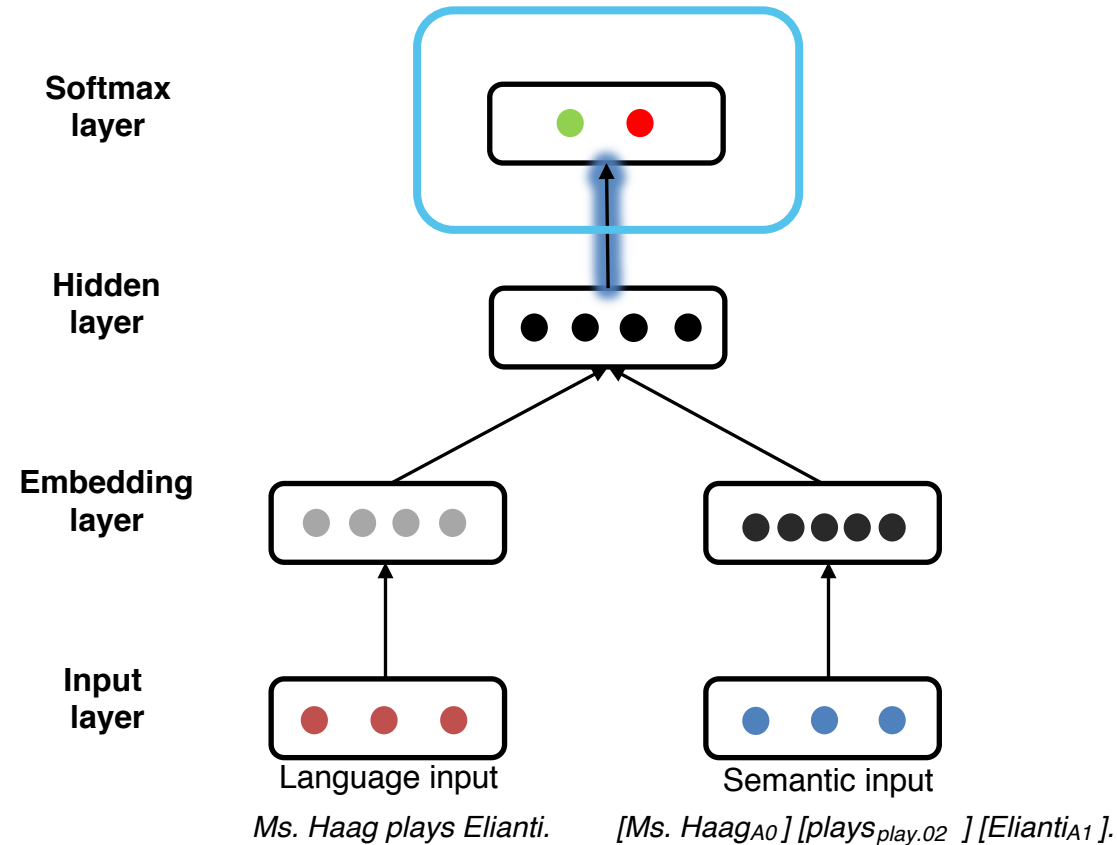
Hidden Layer: Joint Language and Semantic Embedding

- Rectified Linear Units (ReLU): $\vec{h} = \max(0, \mathbf{W}^{e_L h} \vec{e}_L + \mathbf{W}^{e_S h} \vec{e}_S + \vec{b}^h)$



Softmax Layer $q(y = n | \vec{h}) = \frac{e^{\mathbf{W}_n^{eL^s} \vec{e}_L + \mathbf{W}_n^{eS^s} \vec{e}_S + \mathbf{W}_n^{hs} \vec{h} + \vec{b}_n^s}}{\sum_{k=1}^{|K|} e^{\mathbf{W}_k^{eL^s} \vec{e}_L + \mathbf{W}_k^{eS^s} \vec{e}_S + \mathbf{W}_k^{hs} \vec{h} + \vec{b}_k^s}}$

- **Human-free SRL label**
- **Human-need SRL label**



Method	Setting	TEST _{id}			TEST _{od}		
		P	R	F1	P	R	F1
MATE	Initial	86.11	81.11	83.53	75.70	68.38	71.86
	ACTIVESRL_{nj}	87.87	82.45	84.78	76.25	70.47	73.25
	ACTIVESRL	87.69	83.42	85.50	76.79	71.27	73.93
	Upper Bound	89.59	86.87	87.79	79.46	74.21	76.74
CLEAR	Initial	82.07	70.57	75.89	72.77	62.14	67.09
	ACTIVESRL_{nj}	83.12	72.27	77.52	73.82	62.57	67.44
	ACTIVESRL	83.65	73.74	78.38	74.37	66.90	70.48
	Upper Bound	84.74	74.47	79.27	75.44	67.20	71.08
K-SRL	Initial	89.54	80.50	84.78	81.39	69.34	74.88
	ACTIVESRL_{nj}	90.87	82.98	86.48	82.15	71.27	76.33
	ACTIVESRL	91.05	84.44	87.62	82.67	72.74	77.39
	Upper Bound	91.21	87.42	89.28	82.89	77.84	79.91

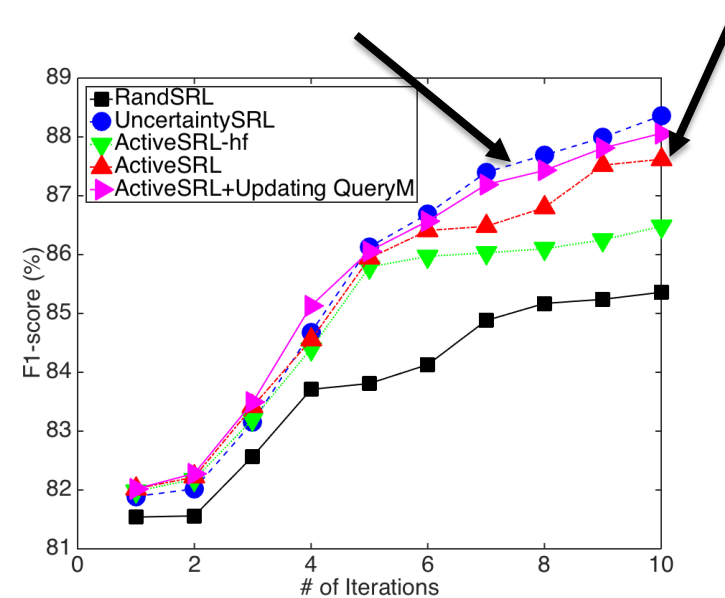
Effective for popular SRL models

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Effective for popular SRL models

Active learning for white-box SRL

Active learning for black-box SRL



Comparable to active learning for white-box SRL (model details are known)

- Active learning framework for black-box SRL models
- Neural query strategy model to learn the strategy for selecting the data instances

- Active learning framework for black-box SRL models
- Neural query strategy model to learn the strategy for selecting the data instances

More importantly, if you have no knowledge about the model, or you are too lazy to design a query strategy for active learning, just try our approach 😊